INTEGRATED CIRCUITS

DATA SHEET

SA7016

1.3GHz low voltage fractional-N synthesizer

Objective specification Supersedes data of 1998 Apr 06





1.3GHz low voltage fractional-N synthesizer

SA7016

FEATURES

- Low phase noise
- Low power
- Fully programmable main divider
- Internal fractional spurious compensation
- Hardware and software power down

APPLICATIONS

- 500-1300 MHz wireless equipment
- Cellular phones
- Portable battery-powered radio equipment.

General description

The SA7016 BICMOS device integrates programmable dividers, charge pumps and a phase comparator to implement a phase-locked loop. The device is designed to operate from 3 NiCd cells, in pocket phones, with low current and nominal 3 V supplies.

The synthesizer operates at VCO input frequencies up to 1.3 GHz. The synthesizer has fully programmable main and reference dividers. All divider ratios are supplied via a 3-wire serial programming bus.

Separate power and ground pins are provided to the analog and digital circuits. The ground leads should be externally short-circuited to prevent large currents flowing across the die and thus causing damage. V_{DDCP} could be greater than or equal to V_{DD} .

The charge pump current (gain) is fixed by an external resistance at pin Rset (pin). Only passive loop filters are used; the charge-pump operates within a wide voltage compliance range to provide a wider tuning range.

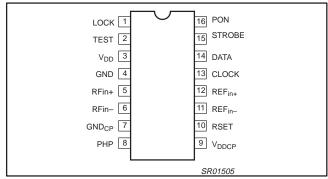


Figure 1. Pin Configuration

QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V_{DD}	Supply voltage	V _{DD}	2.7	-	5.5	V
V _{DDCP}	Analog supply voltage	$V_{DDCP} \ge V_{DD}$	2.7	-	5.5	V
I _{DDCP} +I _{DD}	Supply current		-	6.2	7.3	mA
I _{DDCP} +I _{DD}	Total supply current in power-down mode		-	1	-	μΑ
f _{VCO}	Input frequency		500	-	1300	MHz
f _{REF}	Crystal reference input frequency		10	-	40	MHz
f _{PC}	Maximum phase comparator frequency		-		4	MHz
T _{amb}	Operating ambient temperature		-40	_	+85	°C

ORDERING INFORMATION

TYPE NUMBER	PACKAGE		
TIPE NOWBER	NAME	DESCRIPTION	VERSION
SA7016	TSSOP16	Plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1

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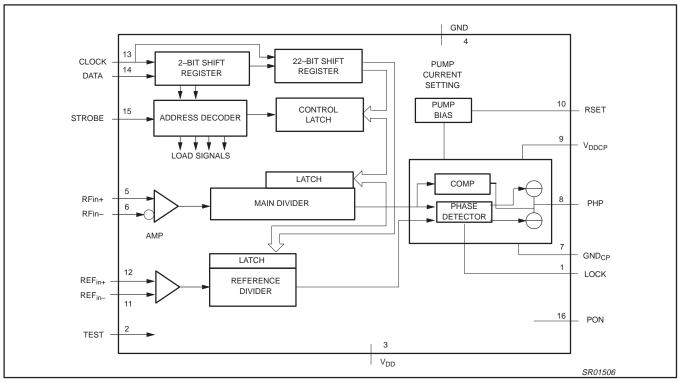


Figure 2. Block Diagram

PINNING

SYMBOL	PIN	DESCRIPTION
LOCK	1	Lock detect output
TEST	2	Test
V _{DD}	3	Digital supply
GND	4	Digital ground
RFin+	5	RF positive input to main divider
RFin-	6	RF negative input to main divider
GND _{CP}	7	Charge pump ground
PHP	8	Main NORMAL chargepump
V _{DDCP}	9	Charge pump supply voltage
RSET	10	External resistor from this pin to ground sets the chargepump current
REF _{in} _	11	Reference input
REF _{in+}	12	Reference input
CLOCK	13	Programming bus clock input
DATA	14	Programming bus data input
STROBE	15	Programming bus enable input
PON	16	Power down control

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Characteristics

 $V_{DDCP} = V_{DD} = +3.0V$, $T_{amb} = +25$ °C; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply; pins	s 3, 9	•	•		•	
V _{DD}	Digital supply voltage		2.7	-	5.5	V
V _{DDCP}	Analog supply voltage	$V_{DDCP} = V_{DD}$	2.7	_	5.5	V
I _{DDTotal}	Synthesizer operational digital supply current	V _{DD} = +3.0V	-	6.2	7.3	mA
I _{standby}	Total supply current in power-down mode	logic levels 0 or VDD	-	1	TBD	μΑ
RFin main d	livider input; pins 5, 6					
f _{VCO}	VCO input frequency		500	-	1300	MHz
V _{RFin(rms)}	AC-coupled input signal level	$R_s = 50 \Omega$; MAX. limit is indicative	-18	-	0	dBm
Z _{IRFin}	Input impedance (real part)	f _{VCO} = 1.0 GHz	-	TBD	-	kΩ
C _{IRFin}	Typical pin input capacitance	indicative, not tested	-	TBD	-	pF
N _m	Main divider ratio		512	_	65535	
f _{PCmax}	Maximum loop comparison frequency	indicative, not tested	-	_	4	MHz
Reference d	livider input; pins 11, 12	•		•	•	•
f _{REFin}	Input frequency range from crystal		10	_	40	MHz
VRFin	AC-coupled input signal level	$R_S=50\Omega$; MAX. limit is indicative	360	-	1300	mVpp
Z _{REFin}	Input impedance (real part)		-	TBD	-	kΩ
C _{REFin}	Typical pin input capacitance	indicative, not tested	-	TBD	-	pF
R _{REF}	Reference division ratio		4	_	1023	
Charge pum	np current setting resistor input; pin 10		•	•	•	
R _{SET}	External resistor from pin 3 to ground		6	7.5	24	kΩ
V _{SET}	Regulated voltage at pin 3	R _{SET} =7.5 kΩ	_	1.25	-	V
Charge pum	p outputs (including fractional compensation pump);	pins 8; R _{SET} =7.5 kΩ, FC	=80			
Icp	Charge pump current ratio to Iset	Current gain I _{PH} /I _{SET}	-15		+15	%
I _{MATCH}	Sink-to-source current matching	V _{ph} =1/2 V _{DDCP} .	-10		+10	%
I _{ZOUT}	Output current variation versus Vph ²	V _{ph} in compliance range	-10		+10	%
I _{LPH}	Charge pump off leakage current	V _{cp} =1/2 V _{CC}	-10		+10	nA
V _{ph}	Charge pump voltage compliance		0.7	_	V _{DDCP} -0.8	V
Phase noise						
C/N	Synthesizer's contribution to close-in-phase noise of 1300 MHz RF signal at 1 kHz offset.	fref=19.44MHz; fcomp=240kHz indicative, not tested	_	-77	-	dBc Hz

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Interface log	jic input signal levels; pins 3, 11, 12, 14, 15, 16					
V _{IH}	HIGH level input voltage		0.7*V _{DD}	-	V _{DD} +0.3	V
V _{IL}	LOW level input voltage		-0.3	-	0.3*V _{DD}	٧
I _{bias}	Input bias current	logic 1 or logic 0	- 5	-	+5	μΑ
Lock detect	output signal (in push/pull mode); pin 1					
V _{OL}	LOW level output voltage	I _{sink} =2mA	_	_	0.4	V
V _{OH}	HIGH level output voltage	I _{source} =-2mA	V _{DD} -0.4	-	-	V

NOTES:

1.
$$I_{SET} = \frac{V_{SET}}{R_{SET}}$$
 bias current for charge pumps.

2. The relative output current variation is defined thus:

$$\frac{\Delta I_{OUT}}{I_{OUT}} = 2 \cdot \frac{(I_2 - I_1)}{I(I_2 + I_1)I}; \text{ with } V_1 = 0.7V, \ V_2 = V_{DDCP} - 0.8V \text{ (See Figure 3.)}$$

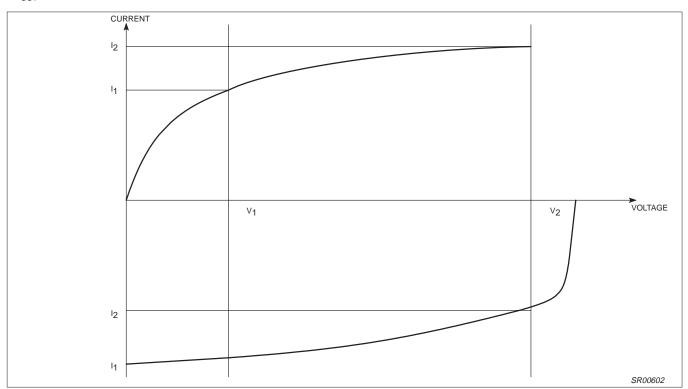


Figure 3. Relative Output Current Variation

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LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
V_{DD}	Digital supply voltage	-0.3	+5.5	V
V_{DDCP}	Analog supply voltage	-0.3	+5.5	V
$\Delta V_{DDCP} - V_{DD}$	Difference in voltage between $V_{DDCP \text{ and }} V_{DD} (V_{DDCP} \ge V_{DD})$	-0.3	+2.8	V
V _n	Voltage at pins 1, 2, 5, 6, 11 to 16	-0.3	V _{DD} + 0.3	V
V ₁	Voltage at pin 8, 9	-0.3	V _{DDCP} + 0.3	V
ΔV_{GND}	Difference in voltage between GND _{CP} and GND (these pins should be connected together)	-0.3	+0.3	V
P _{tot}	Total power dissipation		TBD	mW
T _{stg}	Storage temperature	- 55	+125	°C
T _{amb}	Operating ambient temperature	-30	+85	°C
Tj	Maximum junction temperature		TBD	°C

Handling

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take normal precautions appropriate to handling MOS devices.

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R _{th j–a}	Thermal resistance from junction to ambient in free air	120	K/W

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FUNCTIONAL DESCRIPTION

Main Fractional-N divider

The RFin input (pins 5 and 6) drive a pre-amplifier to provide the clock to the first divider stage. For single ended operation, the signal should be fed to one of the inputs while the other one is AC grounded. The pre-amplifier has a high input impedance, dominated by pin and pad capacitance. The circuit operates with signal levels from –18dBm to +0dBm, and at frequencies as high as 2.5 GHz. The divider consists of a fully programmable bipolar prescaler followed by a CMOS counter. Divide ratios (512 to 65536) allow a minimum phase comparison frequency of 25kHz at 2.5 GHz RF.

At the completion of a main divider cycle, a main divider output pulse is generated which will drive the main phase comparator. Also, the fractional accumulator is incremented by the value of NF. The accumulator works with modulo Q set by FMOD. When the accumulator overflows the overall division ratio N will be increased by 1 to N + 1, the average division ratio over Q main divider cycles (either 5 or 8) will be

$$Nfrac = N + \frac{NF}{Q}$$

The output of the main divider will be modulated with a fractional phase ripple. The phase ripple is proportional to the contents of the

fractional accumulator and is nulled by the fractional compensation charge pump.

The reloading of a new programming word is synchronized to the state of the main divider to avoid introducing a phase disturbance.

Reference divider

The reference divider consists of a divider with programmable values between 4 and 1023 followed by a three bit binary counter. The 3 bit SM (SA) register (see figure 4) determines which fo the 5 output pulses are selected as the main (auxiliary) phase detector input.

Phase detector

The reference and main (aux) divider outputs are connected to a phase/frequency detector that controls the charge pump. The pump current is set by a an external resistor. The dead zone (caused by finite time taken to switch the current sources on or off) is cancelled by forcing the pumps ON for a minimum time at every cycle (backlash time) providing improved linearity.

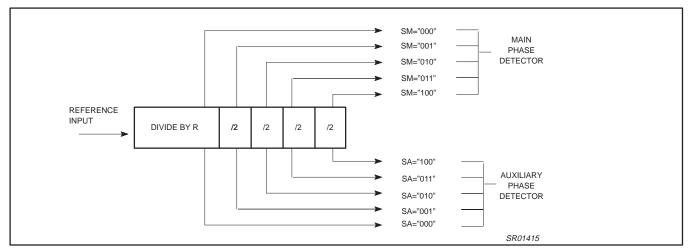


Figure 4. Reference Divider

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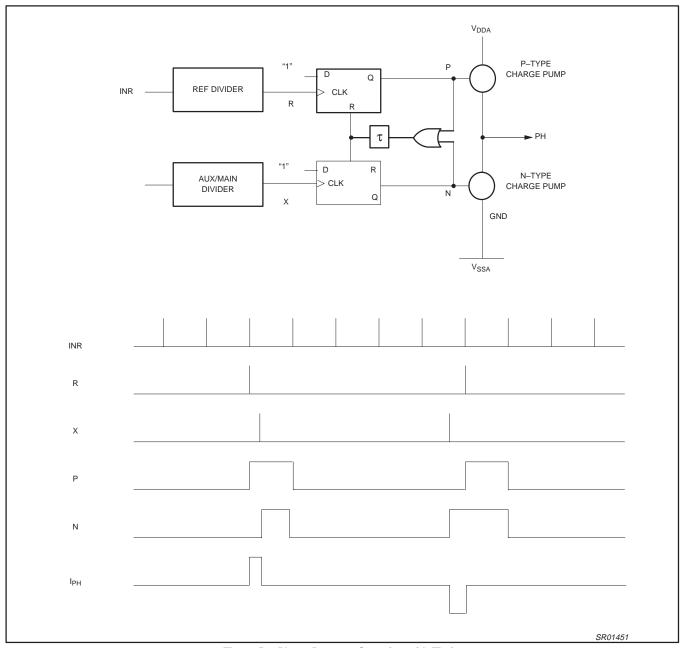


Figure 5. Phase Detector Struction with Timing

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Main Output Charge Pumps and Fractional **Compensation Currents.**

The main charge pumps on pins PHP and PHI are driven by the main phase detector and the charge pump current values are determined by the current at pin RSET. The fractional compensation is derived from the current at RSET, the contents of the fractional accumulator FRD and by the program value of the FDAC. The timing for the fractional compensation is derived from the main divider. See table of charge pump ratios.

Principle of Fractional Compensation

The fractional compensation is designed into the circuit as a means of reducing or eliminating fractional spurs that predominate when the accumulator rolls over and the main divider counts one extra RF input cycle (+1, swallows a cycle). Since I_{COMP} is the compensation current and I_{PUMP} is the pump current, for each charge pump,

I_{PUMP} TOTAL = I_{PUMP} + I_{COMP}

The theoretical values for FDAC are: 128 for FMOD = 1 (modulo 5) and 80 for FMOD = 0 (modulo 8). Fractional division will cause the pump to output a charge that is compensated for in order to reduce fractional spurs. This compensation is done by sourcing a small current, i_A, see Figure 7, that is proportional to the fractional error phase. Figure 6 shows that for proper fractional compensation, the area of the fractional compensation current pulse must be equal to the area of the charge pump ripple.

This means $I_{PUMP}^*Q=I_{COMP}^*128$, where Q equals fractional-N modulus e.g., 2/5 for NF = 2 and FMOD = 1. The fractional compensation current is derived from the main charge pump in that it follows all the current scaling through external resistor setting, RN, programming or speed-up operation. For a given pump,

 $I_{COMP} = (I_{PUMP} / 128) * (FDAC / 5*128) * FRD$

FRD is the fractional accumulator value.



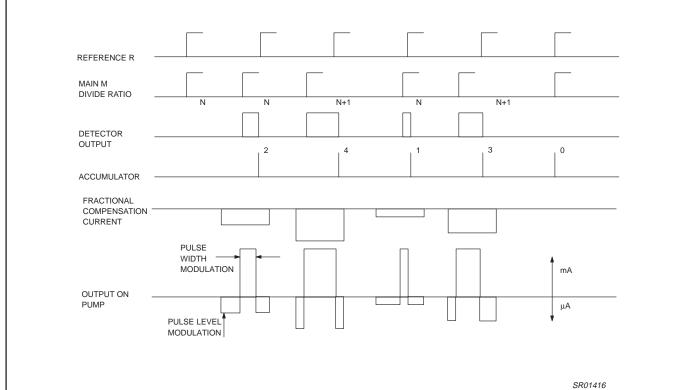


Figure 6. Waveforms for NF = 2, Fraction = 0.4

Fig 6. shows that for a proper fractional compensation, the area of the fractional compensation current pulse must be equal to the area of the charge pump ripple output.

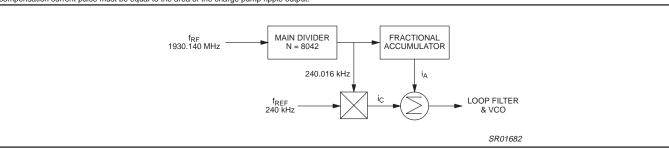


Figure 7. Current Injection Concept

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Charge pump currents

CP0	I _{PHP}	I _{PHP-SU}
0	3xlset	15xlset
1	1xlset	5xlset

- I_{SET}=Vset/_{Rset}: bias current for charge pumps.
 I_{PHP}SU is the total current at pin PHP during speed up condition.

Lock Detect

The output LOCK maintains a logic '1' when the auxiliary phase detector ANDed with the main phase detector indicates a lock condition. The lock condition for the main and auxiliary synthesizers is defined as a phase difference of less than $\pm\,1$ period of the frequency at the input REFin+, -. One counter can fulfill the lock condition when the other counter is powered down. Out of lock (logic '0') is indicated when both counters are powered down.

Power-down mode

The power-down signal can be either hardware (PON) or software (PD). The PON signal is exclusively ORed with the PD bits. If PON = 0, then the part is powered up when PD = 1. PON can be used to invert the polarity of the software bit PD. When the synthesizer is reactivated after the power-down the main and reference dividers are synchronized to avoid possibility of random phase errors on power-up.

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Serial programming bus

The serial input is a 3-wire input (CLOCK, STROBE, DATA) to program all counter divide ratios, fractional compensation DAC, selection and enable bits. The programming data is structured into 24 bit words; each word includes 2 address bits. Figure 8 shows the timing diagram of the serial input. When the STROBE goes active HIGH, the clock is disabled and the data in the shift register remains unchanged. Depending on the 2 address bits the data is latched into

different working registers or temporary registers. In order to fully program the synthesizer, 3 words must be sent: C, B, and A. Table 1 shows the format and the contents of each word. The D word is for testing purposes only. The data for the fractional compensation DAC, FC is stored by the B word in temporary registers. When the A word is loaded, the data of these temporary registers is loaded together with the main divider ratio.

Serial bus timing characteristics. See Figure 8.

 $V_{DD} = V_{DDCP} = +3.0V$; $T_{amb} = +25^{\circ}C$ unless otherwise specified.

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT
Serial program	ming clock; CLK	•			
t _r	Input rise time	_	10	40	ns
t _f	Input fall time	_	10	40	ns
T _{cy}	Clock period	100	_	_	ns
Enable program	nming; STROBE				
t _{START}	Delay to rising clock edge	40	_	_	ns
t _W	Minimum inactive pulse width	1/fcomp	_	_	ns
T _{SU;E}	Enable set-up time to next clock edge	20	_	_	ns
Register serial	input data; DATA				
t _{SU;DAT}	Input data to clock set-up time	20	_	_	ns
t _{HD;DAT}	Input data to clock hold time	20	_	_	ns

Application information

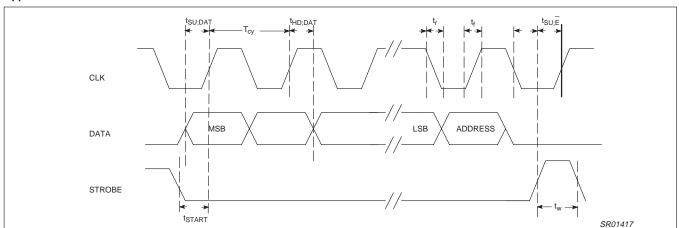


Figure 8. Serial Bus Timing Diagram

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Data format

Table 1. Format of programmed data

LAST IN		MSB	:	SERIAL PROGRA	MMING FORMAT		FIRST IN LSB
p23	p22	p21	p20	/	/	p1	р0

Table 2. A word, length 24 bits

LAST	T IN					MSB														LSB	FIR	ST IN
Address fmod Fractional-N Main Divider ratio										Spare												
0	0	FM	NF2	NF1	NF0	N15	5 N14 N13 N12 N11 N10 N9 N8 N7 N6 N5 N4 N3 N2 N1 N0										N0	SK1	SK2			
Defa	Default: 0 0 1 0 0 0 1 0 0 1 0 0 0 1 1 0 0 0 0										0	0	0									
A wo	rd sele	ct			Fixed	to 00.																
Fract	ional N	1odulus	selec	t	FM 0	= modu	lo 8, 1	= mc	dulo	5.												
Fract	Fractional-N Increment NF20 Fractional N Increment values 000 to 111.																					
N-Div	N-Divider NoN15, Main divider values 512 to 65535 allowed for divider ratio.																					

Table 3. B word, length 24 bits

ADDR	ESS			F	REFER	RENC	E DI\	/IDEF	₹			LO	СК	P	D		FRAC	TION	AL C	ОМРЕ	NSAT	ION DA	AC .
0	1	R9	R8	R7	R6	R5	R4	R3	R2	R1	R0	L1	L0	Main	Aux	FC7	FC6	FC5	FC4	FC3	FC2	FC1	FC0
Defa	ıult:	0	0	0	1 0 1 0 0 0 1 0 0 1 0 0 1 1 0 0 0									0	0								
B word	selec	t			Fixed	to 0	1			•			•			•	•						
R-Divid	der				R0F	R9, R	efere	nce di	vider	value	s 4 to	102	3 allo	wed for	divider	ration							
Lock d	etect o	utput			11	Com Com Main Auxil	bined lock iary lo	main detectop lo	, aux t sign ck de	, lock al pre etect s	deted esent signal	ct sigr at the prese	nal pro LOC ent at	esent at esent at K pin. the LOO down m	the LO	CK pi	n (ope	n draí	n).				
Power	down	Main = 1: power to N-divider, reference divider, main charge pumps, Main = 0 to power down. Aux = 1: power to Aux divider, reference divider, aux charge pump, Aux = 0 to power down.																					
Fractio	nal Co	mper	nsatio	n	FC7.						n cha	rge p	ump (current [DAC, va	alues () to 25	5. Re	comm	ended	value	s: FC =	80 for

Table 4. C word, length 24 bits

Address			Auxiliary Divider										С	Р		SM			SA				
1	0	A13	A13 A12 A11 A10 A9 A8 A7 A6 A5 A4 A3 A2 A1 A0 CP1 CP0 SM2 SM1 SM0 SA2 S								SA1	SA0											
Def	ault	0	0	0	0	0	1	1	1	0	0	1	0	1	0	1	1	0	0	0	0	0	0
C wor	C word select					Fixed to 10																	
A-Div	der				A0A	13, A	uxilia	ry div	ider ر	/alues	128	to 16	384 a	llowe	d for	divide	r ratio.						
Charg	e pum	p curre	ent Ra	tio	CP1,	CP0:	Cha	rge pı	ump c	currer	t ratio	, see	table	of ch	narge	pump	curre	nts.					
Main	Main comparison select SM comparison divider select for main phase detector.																						
Aux c	ompari	son se	elect		SA	Com	oarisc	n div	ider s	elect	for au	ıxiliar	y pha	se de	etecto	r.							

Table 5. D word, length 24 bits

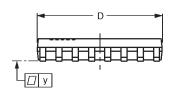
Α	DD	RES	S	S۱		ESIZE BITS	R TES	ST							SYN.	THES	IZER 1	ΓEST	BITS					
1		1	0	-	-	_	_	_	Tspu	_	_	_	_	_	_	-	_	-	-	_	_	_	_	_
	DEF	AUL	Τ.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Tsp	u: S	Spee	d up						synth test bi								the tin	ne.						

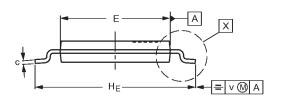
1.3GHz low voltage fractional-N frequency synthesizer

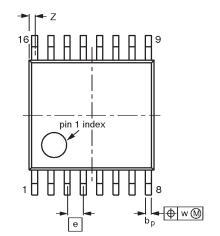
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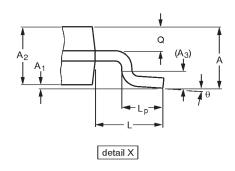
TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

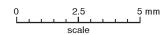
SOT403-1











DIMENSIONS (mm are the original dimensions)

UNIT	A max.	Α1	A ₂	A ₃	рb	c	D ⁽¹⁾	E ⁽²⁾	Φ	HE	٦	Lp	Ø	ν	w	у	Z ⁽¹⁾	θ
mm	1.10	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1.0	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.40 0.06	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	RENCES	EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	EIAJ	PROJECTION	ISSUE DATE
SOT403-1		MO-153			-94-07-12 95-04-04

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Data sheet status

Data sheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make chages at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

^[1] Please consult the most recently issued datasheet before initiating or completing a design.

Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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